TCP Friendly Rate Control (TFRC): Protocol Specification
draft-ietf-dccp-rfc3448bis-04.txt
Abstract

This document specifies TCP-Friendly Rate Control (TFRC). TFRC is a congestion control mechanism for unicast flows operating in a best-effort Internet environment. It is reasonably fair when competing for bandwidth with TCP flows, but has a much lower variation of throughput over time compared with TCP, making it more suitable for applications such as streaming media where a relatively smooth sending rate is of importance.
Table of Contents

1. Introduction ..................................................11
2. Conventions ...................................................12
3. Protocol Mechanism ............................................12
   3.1. TCP Throughput Equation ..................................13
   3.2. Packet Contents ..........................................15
      3.2.1. Data Packets ......................................15
      3.2.2. Feedback Packets ..................................16
4. Data Sender Protocol ..........................................16
   4.1. Measuring the Segment Size ...............................17
   4.2. Sender Initialization ....................................18
   4.3. Sender Behavior When a Feedback Packet is Received ......18
   4.4. Expiration of Nofeedback Timer ...........................21
   4.5. Reducing Oscillations ....................................24
   4.6. Scheduling of Packet Transmissions .......................25
5. Calculation of the Loss Event Rate (p) ........................26
   5.1. Detection of Lost or Marked Packets ......................26
   5.2. Translation from Loss History to Loss Events .............27
   5.3. Inter-loss Event Interval ................................29
   5.4. Average Loss Interval ....................................29
   5.5. History Discounting ......................................30
6. Data Receiver Protocol ........................................32
   6.1. Receiver Behavior When a Data Packet is Received .........33
   6.2. Expiration of Feedback Timer .............................34
   6.3. Receiver Initialization ..................................35
      6.3.1. Initializing the Loss History after the First Loss
             Event ....................................................36
7. Sender-based Variants .........................................37
8. Implementation Issues .........................................37
   8.1. Computing the Throughput Equation ........................38
   8.2. Sender Behavior When a Feedback Packet is Received ......38
      8.2.1. Determining If an Interval Was a Data-limited
             Interval .................................................38
      8.2.2. Maintaining X_recv_set ............................39
   8.3. Sending Packets Before their Nominal Send Time ..........40
   8.4. Calculation of the Average Loss Interval .................41
   8.5. The Optional History Discounting Mechanism ...............41
9. Changes from RFC 3448 .........................................42
   9.1. Overview of Changes ......................................42
   9.2. Changes in each Section ..................................42
10. Security Considerations ......................................45
11. IANA Considerations ..........................................45
12. Acknowledgments ..............................................45
A. Terminology ...................................................46
B. The Initial Value of the Nofeedback Timer .....................48
C. Response to Idle or Data-limited Periods .....................49
   C.1. Long Idle or Data-limited Periods .......................50
NOTE TO RFC EDITOR: PLEASE DELETE THIS NOTE UPON PUBLICATION.

Changes from draft-ietf-dccp-rfc3448bis-03.txt:

* Added text that the choice of b=1 is consistent with RFC3465bis.
  Feedback from Gorry.

* Typos and such reported by Arjuna.

* Updated terminology section, fixed typos and such.
  Feedback from Vladimir Moltchanov.

* Added a section to the Appendix about how one would add CWV-styoe behavior to TFRC for data-limited periods, if one wanted to. Feedback from Gorry.

* Added an implementation section about X_recv_set.

Changes from draft-ietf-dccp-rfc3448bis-02.txt:

* In a data-limited period, instead of setting the receive rate to Infinity, set it to the maximum of (X_recv, values in X_recv_set). Step (4) of Section 4.3.

* Added a fix so that when data-limited and p = 0, the sender doesn’t double the allowed sending rate after each feedback packet. Step (4) of Section 4.3. Problem reported by Arjuna.

* Added a line to the pseudocode for reducing the sending rate during idle periods during initial slow-start. This fixes a problem when the sender is in initial slow-start, has an allowed sending rate less than twice the initial sending rate, and has been idle since the nofeedback timer was set. Step (1) of Section 4.4. Problem reported by Arjuna.

* Added one line to the pseudocode in Section 4.4 on "Expiration of Nofeedback Timer" so that when the nofeedback timer expires and the sender does not have an RTT sample and has not yet received feedback from the receiver, we also look at whether the sender has been idle during the entire nofeedback interval.

* General editing from feedback from Colin Perkins.

* General editing from feedback from Gerrit Renker. This includes the following:
  - Added a subsection to Section 8 on implementation issues about "Sender Behavior When a Feedback Packet is Received".
  - Moved Section 4.6.1 on "Sending Packets Before their Nominal
* Added a subsection on "Evaluating TFRC’s Response to Idle Periods" to the Appendix, encouraging future work on TFRC’s responses to idle and data-limited periods.

Changes from draft-ietf-dccp-rfc3448bis-01.txt:

* Specified that the sender is not limited by the receive rate if the sender has been data-limited for an entire feedback interval.

* Added variables "initial_rate" and "recover_rate," for the initial transmit rate and the rate for resuming after an idle period, for easier specification of Faster Restart (in a separate document). Also added the variable "recv_limit" to specify the limit on the sending rate that is computed from the receive rate, and the variable "timer_limit" to specify the limit on the sending rate from the expiration of the nofeedback timer. Explained why recover_rate is not used as lower bound for nofeedback timer expirations after a data-limited period.

* Added Appendix C on "Response to Idle or Data-limited Periods".

* Revised the section on "Scheduling of Packet Transmissions" to make clear what is specification, and what is implementation. From Gerrit Renker. Also stated that the accumulation of sending credits should be limited to a round-trip time’s worth of packets.

* For measuring the receive rate, added that after a loss event, the receive rate SHOULD be measured over the most recent RTT, but for simplicity of implementation, MAY be measured over a slightly longer time interval.

* Clarified that RTT measurements do not necessarily come from feedback packets; they could also come from other places, e.g., from the SYN exchange.

* Specified that the sender may maintain unused sent credits up to one RTT. This gives behavior similar to TCP. Also specified that the sender should not sent packets more that rtt/2 seconds before their nominal send time.

* Reinserted the last paragraph of Section 4.4 from RFC 3448. It must have been deleted accidently.
* TODO in ns-2
  - Add a variable to ns-2 to allow either TFRC or CCID3.

* Feedback from Arjuna Sathiaseelan:
  - Changing W_init to be in terms of segment size s, not MSS.

* Changed THRESHOLD, the lower bound on the history
discounting parameter DF, from 0.5 to 0.25, for more
history discounting when the current interval is long.

* Relying on the sender not to use X_recv from data-limited
  periods. This gives behavior similar to TCP, when
  ACK-clocking is not in effect in data-limited periods.
The largest X_recv over the most recent two round-trip
times is used to limit the sending rate. This is
  maintained using X_recv_set. Taken together, these avoid
  problems with the first feedback packet after an idle
  period, and this avoids problems with limitations
  from X_recv during data-limited periods.

* Clarified that when the receiver receives a data packet,
  and didn’t send a feedback packet when the feedback timer
  last expired (because no data packets were received),
  then the receiver sends a feedback packet immediately.

* Clarified that the feedback packet reports the rate over
  the last RTT, not necessarily the rate since the
  last feedback packet was sent (if no feedback packet was
  sent when the feedback timer last expired).

* Corrected earlier code designed to prevent the receive
  rate from limiting the sending rate when the first feedback
  packet received, or for the first feedback packet received
  after an idle period.

* Clarified that we have p=0 only until the first loss event.
  After the first loss event, p>0, and it is not possible to go
  back to p=0. In response to old email.

* Clarified in Section 6.1 that the loss event rate does not
  have to be recalculated with the arrival of each new data
  packet.

* Clarified the section on Reducing Oscillations. Feedback from
  Gerrit Renker.

Changes from draft-ietf-dccp-rfc3448bis-00.txt:
* When initializing the loss history after the first
data packet sent is lost or ECN-marked, TFRC uses
a minimum receive rate of 0.5 packets per second.

* For initializing the estimated packet drop rate
for the first loss interval when coming out of slow-start,
it is ok to use the maximum receive rate so far, not just
the receive rate in the last round-trip time.
Feedback from Ladan Gharai.

* General feedback from Gorry Fairhurst:
  - Added a reference for RFC4828.
  - Clarified that R_m is sender’s estimate of RTT, as reported
    in Section 3.2.1.
  - Added a definition of terms.
  - Added a discussion of why the initial value of the nofeedback
    timer is two seconds, instead of three seconds for the
    recommended initial value for TCP’s retransmit timer.

* General feedback from Arjuna Sathiaseelan:
  - Added more details about sending multiple feedback
    packets per RTT.
  - Added change to Section 4.3 to use the first feedback
    packet, or the first feedback packet after a
    nofeedback timer during slow-start, *if min_rate > X*.

* General feedback from Gerrit Renker:
  - Changed "delta" to "t_delta".
  - Changed X_calc to X_Bps, clarified X.
  - Clarified send times in "Scheduling of Packet Transmissions".
  - Changed so that tld can be initialized to either 0 or -1.
  - Fixed Section 5.5 to say that the most recent lost
    interval has weight 1/(0.75*n) *when there have been
    at least eight loss intervals*.
  - Clarified introduction about fixed-size and variable-size
    packets.

* Added more about sender-based variants.
  Feedback from Guillaume Jourjon.

* Corrected that the loss interval I_0 includes all transmitted
  packets, including lost and marked packets (as defined in Section
  5.3 in the general definition.) Email from Eddie Kohler and
  Gerrit Renker.

* Not done: I didn’t add a minimum value for the nofeedback
  timer. (Why would a nofeedback timer need to be bigger
  than max(4*R, 2*s/X)? Email discussing pros and cons from
Arjuna.

Changes from draft-floyd-rfc3448bis-00.txt:

* Name change to draft-ietf-dccp-rfc3448bis-00.txt.

* Specified the receiver's initialization of the feedback timer when the first data packet doesn't have an estimate of the RTT. From feedback from Dado Colussi.

* Added the procedure for sending receiver feedback packets when a coarse-grained timestamp is used. From RFC 4243.

Changes from RFC 3448:

* Incorporated changes in the RFC 3448 errata:

  - "If the sender does not receive a feedback report for four round trip times, it cuts its sending rate in half." ("Two" changed to "four", for consistency with the rest of the document. Reported by Joerg Widmer).

  - "If the nofeedback timer expires when the sender does not yet have an RTT sample, and has not yet received any feedback from the receiver, or when p == 0,..." (Added "or when p == 0," reported by Wim Heirman).

  - In Section 5.5, changed:
    
    \[
    \text{for (i = 1 to n) \{ DF_i = 1; \}}
    
    \] to:
    
    \[
    \text{for (i = 0 to n) \{ DF_i = 1; \}}
    
    \] Reported by Michele R.

* Changed RFC 3448 to correspond to the larger initial windows specified in RFC 3390. This includes the following:

  - Incorporated Section 5.1 from [RFC4342], saying that when reducing the sending rate after an idle period, do not reduce the sending rate below the initial sending rate.

  - Change for a data-limited sender: When the sender has been data-limited, the sender doesn’t let the receive rate limit it to a sending rate less than the initial rate.

  - Small change to slow-start: Changed so that for the first feedback packet received,
or for the first feedback packet received after an idle period, the receive rate is not used to limit the sending rate. This is because the receiver might not yet have seen an entire window of data.

* Clarified how the average loss interval is calculated when the receiver has not yet seen eight loss intervals.

* Discussed more about estimating the average segment size:

  - For initializing the loss history after the first loss event, either the receiver knows the sender’s value for s, or the receiver uses the throughput equation for X_pps and does not need to know an estimate for s.

  - Added a discussion about estimating the average segment size s in Section 4.1 on "Measuring the Segment Size".

  - Changed "packet size" to "segment size".

END OF NOTE TO RFC EDITOR.
1. Introduction

This document specifies TCP-Friendly Rate Control (TFRC). TFRC is a congestion control mechanism designed for unicast flows operating in an Internet environment and competing with TCP traffic [FHPW00]. Instead of specifying a complete protocol, this document simply specifies a congestion control mechanism that could be used in a transport protocol such as DCCP (Datagram Congestion Control Protocol) [RFC4340], in an application incorporating end-to-end congestion control at the application level, or in the context of endpoint congestion management [BRS99]. This document does not discuss packet formats or reliability. Implementation-related issues are discussed only briefly, in Section 8.

TFRC is designed to be reasonably fair when competing for bandwidth with TCP flows, where we call a flow "reasonably fair" if its sending rate is generally within a factor of two of the sending rate of a TCP flow under the same conditions. However, TFRC has a much lower variation of throughput over time compared with TCP, which makes it more suitable for applications such as telephony or streaming media where a relatively smooth sending rate is of importance.

The penalty of having smoother throughput than TCP while competing fairly for bandwidth is that TFRC responds slower than TCP to changes in available bandwidth. Thus, TFRC should only be used when the application has a requirement for smooth throughput, in particular, avoiding TCP’s halving of the sending rate in response to a single packet drop. For applications that simply need to transfer as much data as possible in as short a time as possible we recommend using TCP, or if reliability is not required, using an Additive-Increase, Multiplicative-Decrease (AIMD) congestion control scheme with similar parameters to those used by TCP.

TFRC is designed for best performance with applications that use a fixed segment size, and vary their sending rate in packets per second in response to congestion. TFRC can also be used, perhaps with less optimal performance, with applications that do not have a fixed segment size, but where the segment size varies according to the needs of the application (e.g., video applications).

Some applications (e.g., some audio applications) require a fixed interval of time between packets and vary their segment size instead of their packet rate in response to congestion. The congestion control mechanism in this document is not designed for those applications; TFRC-SP (Small-Packet TFRC) is a variant of TFRC for applications that have a fixed sending rate in packets per second but either use small packets, or vary their packet size in response.
This document specifies TFRC as a receiver-based mechanism, with the calculation of the congestion control information (i.e., the loss event rate) in the data receiver rather than the data sender. This is well-suited to an application where the sender is a large server handling many concurrent connections, and the receiver has more memory and CPU cycles available for computation. In addition, a receiver-based mechanism is more suitable as a building block for multicast congestion control. However, it is also possible to implement TFRC in sender-based variants, as allowed in DCCP’s Congestion Control ID 3 (CCID 3) [RFC4342].

2. Conventions

The key words "MUST", "MUST NOT", "REQUIRED", "SHALL", "SHALL NOT", "SHOULD", "SHOULD NOT", "RECOMMENDED", "MAY", and "OPTIONAL" in this document are to be interpreted as described in [RFC2119].

Appendix A gives a list of technical terms used in this document.

3. Protocol Mechanism

For its congestion control mechanism, TFRC directly uses a throughput equation for the allowed sending rate as a function of the loss event rate and round-trip time. In order to compete fairly with TCP, TFRC uses the TCP throughput equation, which roughly describes TCP’s sending rate as a function of the loss event rate, round-trip time, and segment size. We define a loss event as one or more lost or marked packets from a window of data, where a marked packet refers to a congestion indication from Explicit Congestion Notification (ECN) [RFC3168].

Generally speaking, TFRC’s congestion control mechanism works as follows:

- The receiver measures the loss event rate and feeds this information back to the sender.
- The sender also uses these feedback messages to measure the round-trip time (RTT).
- The loss event rate and RTT are then fed into TFRC’s throughput equation, and the resulting sending rate is limited to at most twice the receive rate to give the allowed transmit rate X.
The sender then adjusts its transmit rate to match the allowed transmit rate X.

The dynamics of TFRC are sensitive to how the measurements are performed and applied. We recommend specific mechanisms below to perform and apply these measurements. Other mechanisms are possible, but it is important to understand how the interactions between mechanisms affect the dynamics of TFRC.

3.1. TCP Throughput Equation

Any realistic equation giving TCP throughput as a function of loss event rate and RTT should be suitable for use in TFRC. However, we note that the TCP throughput equation used must reflect TCP’s retransmit timeout behavior, as this dominates TCP throughput at higher loss rates. We also note that the assumptions implicit in the throughput equation about the loss event rate parameter have to be a reasonable match to how the loss rate or loss event rate is actually measured. While this match is not perfect for the throughput equation and loss rate measurement mechanisms given below, in practice the assumptions turn out to be close enough.

The throughput equation we currently recommend for TFRC is a slightly simplified version of the throughput equation for Reno TCP from [PFTK98]. Ideally we would prefer a throughput equation based on SACK TCP, but no one has yet derived the throughput equation for SACK TCP, and from both simulations and experiments, the differences between the two equations are relatively minor.

The throughput equation is:

\[
X_{\text{Bps}} = \frac{s}{R \sqrt{2bp/3} + (t_{\text{RTO}} \times (3\sqrt{3bp/8}p(1+32p^2)))}
\]

Where:

- \(X_{\text{Bps}}\) is the transmit rate in bytes/second. (\(X_{\text{Bps}}\) is the same as \(X_{\text{calc}}\) in RFC 3448.)
- \(s\) is the segment size in bytes.
- \(R\) is the round trip time in seconds.
- \(p\) is the loss event rate, between 0 and 1.0, of the number of loss events as a fraction of the number of packets transmitted.
t_RTO is the TCP retransmission timeout value in seconds.

b is the maximum number of packets acknowledged by a single TCP acknowledgement.

Setting the TCP retransmission timeout value t_RTO:
We further simplify this by setting t_RTO = 4*R. A more accurate calculation of t_RTO is possible, but experiments with the current setting have resulted in reasonable fairness with existing TCP implementations [W00]. Another possibility would be to set t_RTO to max(4*R, one second), to match the recommended minimum of one second on the RTO [RFC2988].

Setting the parameter b for delayed acknowledgements:
Many current TCP connections use delayed acknowledgements, sending an acknowledgement for every two data packets received, and thus have a sending rate modeled by b = 2. However, TCP is also allowed to send an acknowledgement for every data packet, and this would be modeled by b = 1. Because many TCP implementations do not use delayed acknowledgements, we recommend b = 1. For the revised TCP congestion control mechanisms, [RFC2581bis] currently specifies that the delayed acknowledgement algorithm SHOULD be used with TCP. However, [RFC2581bis] recommends increasing the congestion window during congestion avoidance by one segment per RTT even in the face of delayed acknowledgements, consistent with a TCP throughput equation with b = 1. On an experimental basis, [RFC2581bis] allows for increases of the congestion window during slow-start that are also consistent with a TCP throughput equation with b = 1. Thus, the use of b = 1 is consistent with [RFC2581bis].

With t_RTO=4*R and b=1, the throughput equation can be simplified as:

\[
X_{Bps} = \frac{s}{R \ast (\sqrt{2p/3} + 12\sqrt{3p/8} \ast p \ast (1+32\ast p^2))}
\]

In future, different TCP equations may be substituted for this equation. The requirement is that the throughput equation be a reasonable approximation of the sending rate of TCP for conformant TCP congestion control.

The throughput equation can also be expressed as

\[X_{Bps} = X_{pps} \ast s\]

with X_{pps}, the sending rate in packets per second, given as
1
X_{pps} = \frac{R \sqrt{2bp/3} + (t_{RTO} \sqrt{3b/8p^3} + p(1+32p^2))}{\text{The parameters } s \text{ (segment size)}, p \text{ (loss event rate)} \text{ and } R \text{ (RTT)} \text{ need to be measured or calculated by a TFRC implementation. The measurement of } s \text{ is specified in Section 4.1, measurement of } R \text{ is specified in Section 4.3, and measurement of } p \text{ is specified in Section 5. In the rest of this document data rates are measured in bytes/second unless otherwise specified.}}

3.2. Packet Contents

Before specifying the sender and receiver functionality, we describe the contents of the data packets sent by the sender and feedback packets sent by the receiver. As TFRC will be used along with a transport protocol, we do not specify packet formats, as these depend on the details of the transport protocol used.

3.2.1. Data Packets

Each data packet sent by the data sender contains the following information:

- A sequence number. This number is incremented by one for each data packet transmitted. The field must be sufficiently large that it does not wrap causing two different packets with the same sequence number to be in the receiver’s recent packet history at the same time.

- A timestamp indicating when the packet is sent. We denote by \(t_{si}\) the timestamp of the packet with sequence number \(i\). The resolution of the timestamp should typically be measured in milliseconds.

This timestamp is used by the receiver to determine which losses belong to the same loss event. The timestamp is also echoed by the receiver to enable the sender to estimate the round-trip time, for senders that do not save timestamps of transmitted data packets.

We note that as an alternative to a timestamp incremented in milliseconds, a "timestamp" that increments every quarter of a round-trip time would be sufficient for determining when losses belong to the same loss event, in the context of a protocol where this is understood by both sender and receiver, and where...
the sender saves the timestamps of transmitted data packets.

- The sender’s current estimate of the round trip time. The estimate reported in packet $i$ is denoted by $R_i$. The round-trip time estimate is used by the receiver, along with the timestamp, to determine when multiple losses belong to the same loss event. The round-trip time estimate is also used by the receiver to determine the interval to use for calculating the receive rate, and to determine when to send feedback packets.

If the sender sends a coarse-grained "timestamp" that increments every quarter of a round-trip time, as discussed above, then the sender does not need to send its current estimate of the round trip time.

### 3.2.2. Feedback Packets

Each feedback packet sent by the data receiver contains the following information:

- The timestamp of the last data packet received. We denote this by $t_{recvdata}$. If the last packet received at the receiver has sequence number $i$, then $t_{recvdata} = ts_i$. This timestamp is used by the sender to estimate the round-trip time, and is only needed if the sender does not save timestamps of transmitted data packets.

- The amount of time elapsed between the receipt of the last data packet at the receiver, and the generation of this feedback report. We denote this by $t_{delay}$.

- The rate at which the receiver estimates that data was received in the previous round-trip time. We denote this by $X_{recv}$.

- The receiver’s current estimate of the loss event rate $p$.

### 4. Data Sender Protocol

The data sender sends a stream of data packets to the data receiver at a controlled rate. When a feedback packet is received from the data receiver, the data sender changes its sending rate, based on the information contained in the feedback report. If the sender does not receive a feedback report for four round trip times, then the sender cuts its sending rate in half. This is achieved by means of a timer called the nofeedback timer.
We specify the sender-side protocol in the following steps:

- Measurement of the mean segment size being sent.
- Sender initialization.
- The sender behavior when a feedback packet is received.
- The sender behavior when the nofeedback timer expires.
- Oscillation prevention (optional)
- Scheduling of packet transmission and allowed burstiness.

4.1. Measuring the Segment Size

The parameter $s$ (segment size) is normally known to an application. This may not be so in two cases:

1) The segment size naturally varies depending on the data. In this case, although the segment size varies, that variation is not coupled to the transmit rate. The TFRC sender can either compute the average segment size or use the maximum segment size for the segment size $s$.

2) The application needs to change the segment size rather than the number of segments per second to perform congestion control. This would normally be the case with packet audio applications where a fixed interval of time needs to be represented by each packet. Such applications need to have a completely different way of measuring parameters.

For the first class of applications where the segment size varies depending on the data, the sender MAY estimate the segment size $s$ as the average segment size over the last four loss intervals. The sender MAY also estimate the average segment size over longer time intervals, if so desired. The TFRC sender uses the segment size $s$ in the throughput equation, in the setting of the maximum receive rate and the minimum and initial sending rates, and in the setting of the nofeedback timer.

The TFRC receiver may use the average segment size $s$ in initializing the loss history after the first loss event, but Section 6.3.1 also gives an alternate procedure that does not use the average segment size $s$. 
The second class of applications are discussed separately in a separate document on TFRC-SP. For the remainder of this section we assume the sender can estimate the segment size, and that congestion control is performed by adjusting the number of packets sent per second.

4.2. Sender Initialization

The initial values for X (the allowed sending rate in bytes per second) and tld (the Time Last Doubled during slow-start, in seconds) are undefined until they are set as described below. If the sender is ready to send data when it does not yet have a round trip sample, the value of X is set to s bytes per second, for segment size s, the nofeedback timer is set to expire after two seconds, and tld is set to 0 (or to -1, either one is okay). Upon receiving the first round trip time measurement (e.g., after the first feedback packet or the SYN exchange from connection set-up, or from a previous connection [RFC2140]), tld is set to the current time, and the allowed transmit rate X is set to the initial_rate, specified as $W_{init}/R$, for $W_{init}$ based on [RFC3390]:

$$W_{init} = \min(4s, \max(2s, 4380))$$.

For responding to the initial feedback packet, this replaces step (4) of Section 4.3 below.

Appendix B explains why the initial value of TFRC’s nofeedback timer is set to two seconds, instead of the recommended initial value of three seconds for TCP’s retransmit timer from [RFC2988].

4.3. Sender Behavior When a Feedback Packet is Received

The sender knows its current allowed sending rate X, and maintains an estimate of the current round trip time R. The sender also maintains X_recv_set as a small set of recent X_recv values (typically only two values). X_recv_set is first initialized to contain a single item, with value Infinity (or a suitably large number). The variable recv_limit is defined as the limit on the sending rate that is computed from the receive rate. In this document, in step (4) below, recv_limit is specified as twice the maximum value in X_recv_set. Future documents [KFS07] might specify alternate values for recv_limit.

When a feedback packet is received by the sender at time $t_{now}$, the current time in seconds, the following actions should be performed.
1) Calculate a new round trip sample:
   \[ R_{\text{sample}} = (t_{\text{now}} - t_{\text{recvdata}}) - t_{\text{delay}}. \]

2) Update the round trip time estimate:
   
   If no feedback has been received before {
   
   \[ R = R_{\text{sample}}; \]
   
   } Else {
   
   \[ R = q*R + (1-q)*R_{\text{sample}}; \]
   
   }

   TFRC is not sensitive to the precise value for the filter constant \( q \), but we recommend a default value of 0.9.

3) Update the timeout interval:
   \[ RTO = \max(4*R, 2*s/X) \]

4) Update the allowed sending rate as follows. This procedure uses the following new variable:

   \( t_{\text{mbi}} \): the maximum backoff interval of 64 seconds.

   The procedure for updating the allowed sending rate:

   If (the entire interval covered by the feedback packet was a data-limited interval) {
   
   Maximize \( X_{\text{recv_set}} \);
   
   } Else {
   
   Update \( X_{\text{recv_set}} \); \hspace{1cm} // typical behavior
   
   } recv_limit = 2 * max (X_{\text{recv_set}});

   If (\( p > 0 \)) { \hspace{1cm} // congestion avoidance phase
   
   Calculate \( X_{\text{Bps}} \) using the TCP throughput equation.
   
   \[ X = \max(\min(X_{\text{Bps}}, \text{recv_limit}), s/t_{\text{mbi}}); \]
   
   } Else if ((t_now - tld >= R) and (sender was not data-limited over entire feedback interval) {
   
   // initial slow-start
   
   \[ X = \max(\min(2*X, \text{recv_limit}), \text{initial_rate}); \]

   tld = t_now;
   
   }

5) If oscillation reduction is used, calculate the instantaneous transmit rate \( X_{\text{inst}} \), following Section 4.5.
6) Reset the nofeedback timer to expire after RTO seconds.

The subroutine for maximizing X_recv_set keeps a single value, the largest value from X_recv_set and the new X_recv.

Maximize X_recv_set:
   Add X_recv to X_recv_set;
   Set the timestamp of the largest item to the current time;
   Delete all other items.

The subroutine for updating X_recv_set keeps a set of X_recv values with timestamps from the most recent two round-trip times.

Update X_recv_set:
   Add X_recv to X_recv_set;
   Delete from X_recv_set values older than two round-trip times.

Definition of a data-limited interval:
We define a sender as data-limited any time it is not sending as much as it is allowed to send (including unused send credits discussed in Section 4.6). We define an interval as a 'data-limited interval' if the sender was data-limited over the "entire" interval. The first "if" condition in step (4) prevents a sender from having to reduce the sending rate as a result of a feedback packet reporting the receive rate from a data-limited period.

As an example, consider a sender that is sending at its full allowed rate, except that it is sending packets in pairs, rather than sending each packet as soon as it can. Such a sender is considered data-limited part of the time, because it is not always sending packets as soon as it can. However, consider an interval that covers this sender's transmission of at least two data packets; such an interval does not meet the definition of a data-limited interval, because the sender was not data-limited *over the entire interval*.

X_recv_set and the first feedback packet:
Because X_recv_set is initialized with a single item, with value Infinity, recv_limit is set to Infinity for the first two round-trip times of the connection. As a result, the sending rate is not limited by the receive rate during that period. This avoids the problem of the sending rate being limited by the value of X_recv from the first feedback packet, which reports only one segment received in the last round-trip time,
The interval covered by a feedback packet:
How does the sender determine the period covered by a feedback packet? This is discussed in more detail in Section 8.2. In general, the receiver will be sending a feedback packet once per round-trip time, so typically the sender will be able to determine exactly the period covered by the current feedback packet from the previous feedback packet. However, in cases when the previous feedback packet was lost, or when the receiver sends a feedback packet early because it detected a lost or ECN-marked packet, the sender will have to estimate the interval covered by the feedback packet. As specified in Section 6.2, each feedback packet sent by the receiver covers a round-trip time, for the round-trip time estimate R_m maintained by the receiver R_m seconds before the feedback packet was sent.

The initial slow-start phase:
Note that when p=0, the sender has not yet learned of any loss events, and the sender is in the initial slow-start phase. In this initial slow-start phase, the sender can approximately double the sending rate each round-trip time until a loss occurs. The initial_rate term in step (4) gives a minimum allowed sending rate during slow-start of the initial allowed sending rate.

We note that if the sender is data-limited during slow-start, or if the connection is limited by the path bandwidth, then the sender is not necessarily able to double its sending rate each round-trip time; the sender’s sending rate is limited to at most twice the receive rate, or at most initial_rate, whichever is larger. This is similar to TCP’s behavior, where the sending rate is limited by the rate of incoming acknowledgement packets as well as by the congestion window. Thus in TCP’s Slow-Start, for the most aggressive case of the TCP receiver acknowledging every data packet, the TCP sender’s sending rate is limited to at most twice the rate of these incoming acknowledgment packets.

The minimum allowed sending rate:
The term s/t_mbi ensures that when p > 0, the sender is allowed to send at least one packet every 64 seconds.

4.4. Expiration of Nofeedback Timer

This section specifies the sender’s response to a nofeedback timer. The nofeedback timer could expire because of an idle period, or because of data or feedback packets dropped in the network.

This section uses the variable recover_rate. If the TFRC sender has been idle ever since the nofeedback timer was set, the allowed sending rate is not reduced below the recover_rate. For this
document, the recover_rate is set to the initial_rate. Future
documents may explore other possible values for the recover_rate.

If the nofeedback timer expires, the sender should perform the
following actions:

1) Cut the allowed sending rate in half.

   If the nofeedback timer expires when the sender has had at least
   one RTT measurement, the allowed sending rate is reduced by
   modifying X_recv_set as described in the pseudocode below
   (including item (2)). In the general case, the sending rate is
   limited to at most twice X_recv. Modifying X_recv_set limits
   the sending rate, but still allows the sender to slow-start,
   doubling its sending rate each RTT, if feedback messages resume
   reporting no losses.

   If the sender has been idle since this nofeedback timer was set
   and X_recv is less than the recover_rate, then the allowed
   sending rate is not halved, and X_recv_set is not changed. This
   ensures that the allowed sending rate is not reduced to less
   than half the recover_rate as a result of an idle period.

   In the general case, the allowed sending rate is halved in
   response to the expiration of the nofeedback timer. The
details, in the pseudocode below, depend on whether the sender
is in slow-start, is in congestion avoidance limited by X_recv,
or is in congestion avoidance limited by the throughput
equation. We use the variable timer_limit for the limit on the
sending rate computed from the expiration of the nofeedback
timer.
X_recv = max (X_recv_set);
If (sender does not have an RTT sample, 
has not received any feedback from receiver, 
and has not been idle ever since the nofeedback timer was set) {
    // We do not have X_Bps or recover_rate yet. 
    // Halve the allowed sending rate.
    X = max(X/2, s/t_mbi);
} Else if (((p>0 && X_recv < recover_rate) or 
    (p==0 && X < 2 * recover_rate)), and 
    sender has been idle ever 
    since nofeedback timer was set) {
    // Don’t halve the allowed sending rate.
    timer_limit is not updated;
} Else if (p==0) {
    // We do not have X_Bps yet. 
    // Halve the allowed sending rate.
    X = max(X/2, s/t_mbi);
} Else if (X_Bps > 2*X_recv)) {
    // 2*X_recv was already limiting the sending rate.
    // Halve the allowed sending rate.
    timer_limit = X_recv;
} Else {
    // The sending rate was limited by X_Bps, not by X_recv.
    // Halve the allowed sending rate.
    timer_limit = X_Bps/2;
}
If (timer_limit < s/t_mbi) {
    timer_limit = s/t_mbi;
}

The term s/t_mbi limits the backoff to one packet every 64 seconds.

2) If timer_limit has been changed, then do the following:

    If (timer_limit has been updated) {
        Replace X_recv_set contents with the single item timer_limit/2.
        Recalculate X as in step (4) of Section 4.3.
    }

3) Restart the nofeedback timer to expire after max(4*R, 2*s/X) 
seconds.

If the sender has been data-limited but not idle since the 
nofeedback timer was set, it is possible that the nofeedback timer 
expired because data or feedback packets were dropped in the
network. In this case, the nofeedback timer is the backup mechanism for the sender to detect these losses, similar to the retransmit timer in TCP.

Note that when the sender stops sending, the receiver will stop sending feedback. When the sender’s nofeedback timer expires, the sender could use the procedure above to limit the sending rate. If the sender subsequently starts to send again, X_recv_set will be used to limit the transmit rate, and slow-start behavior will occur until the transmit rate reaches X_Bps.

The TFRC sender’s reduction of the allowed sending rate after the nofeedback timer expires is similar to TCP’s reduction of the congestion window cwnd after each RTO seconds of an idle period, for TCP with Congestion Window Validation [RFC2861].

4.5. Reducing Oscillations

To reduce oscillations in queueing delay and sending rate in environments with a low degree of statistical multiplexing at the congested link, it can be useful for the sender to reduce the transmit rate as the queueing delay (and hence RTT) increases. To do this the sender maintains R_sqmean, a long-term estimate of the square root of the RTT, and modifies its sending rate depending on how the square root of R_sample, the most recent sample of the RTT, differs from the long-term estimate. The long-term estimate R_sqmean is set as follows:

\[
\begin{align*}
    \text{If no feedback has been received before} & \quad \text{R} = \sqrt{R_{\text{sample}}} \\
    \text{Else} & \quad \text{R} = q^2 \times \text{R} + (1 - q^2) \times \sqrt{R_{\text{sample}}}
\end{align*}
\]

Thus R_sqmean gives the exponentially weighted moving average of the square root of the RTT samples. The constant q should be set similarly to q, the constant used in the round trip time estimate R. We recommend a value of 0.9 as the default for q2.

When \sqrt{R_{\text{sample}}} is greater than R_sqmean then the current round-trip time is greater than the long-term average, implying that queueing delay is probably increasing. In this case, the transmit rate is decreased to minimize oscillations in queueing delay.

The sender obtains the base allowed transmit rate, X, as described in step (4) of Section 4.3 above. It then calculates a modified instantaneous transmit rate X_inst, as follows:
\[
X_{\text{inst}} = X \times \frac{\text{R}_{\text{sqmean}}}{\sqrt{\text{R}_{\text{sample}}}};
\]

If \( p > 0 \) {  // congestion avoidance phase
    \[
    X_{\text{inst}} = \max(X_{\text{inst}}, \frac{s}{t_{\text{mbi}}})
    \]
} Else if \( (t_{\text{now}} - t_{\text{lid}}) \geq R \) {  // initial slow-start
    \[
    X_{\text{inst}} = \max(X_{\text{inst}}, \frac{s}{R})
    \]
} 

Because we are using square roots, there is generally only a moderate difference between the instantaneous transmit rate \( X_{\text{inst}} \) and the allowed transmit rate \( X \). For example, in a somewhat extreme case when the current RTT sample \( R_{\text{sample}} \) is twice as large as the long-term average, then \( \sqrt{R_{\text{sample}}} \) will be roughly 1.44 times \( R_{\text{sqmean}} \), and the allowed transmit rate will be reduced by a factor of roughly 0.7.

Note: This modification for reducing oscillatory behavior is not always needed, especially if the degree of statistical multiplexing in the network is high. We also note that the measured round-trip time is not necessarily strongly correlated with the data packet queueing delay. However, this modification SHOULD be implemented because it makes TFRC behave better in some environments with a low level of statistical multiplexing. The performance of this modification is illustrated in Section 3.1.3 of [FHPW00]. If it is not implemented, we recommend using a very low value of the weight \( q \) for the average round-trip time.

4.6. Scheduling of Packet Transmissions

As TFRC is rate-based, and as operating systems typically cannot schedule events precisely, it is necessary to be opportunistic about sending data packets so that the correct average rate is maintained despite the coarse-grain or irregular scheduling of the operating system. To help maintain the correct average sending rate, the TFRC sender may send some packets before their nominal send time.

In addition, the scheduling of packet transmissions controls the allowed burstiness of senders after an idle or data-limited period. The TFRC sender is allowed to accumulate sending ‘credits’ for past unused send times; this allows the TFRC sender to send a burst of data after an idle or data-limited period. To compare with TCP, TCP may send up to a round-trip time’s worth of packets in a single burst, but never more. As examples, packet bursts can be sent by TCP when an ACK arrives acknowledging a window of data, or when a data-limited sender suddenly has a window of data to send after a delay of nearly a round-trip time.

To limit burstiness, a TFRC implementation MUST prevent bursts of arbitrary size. This limit MUST be less than or equal to one round-
trip time’s worth of packets. A TFRC implementation MAY limit bursts to less than a round-trip time’s worth of packets, if so desired. However, we note that such limits also constrain TFRC’s performance beyond the case for the current TCP.

As an implementation-specific example, a sending loop could calculate the correct inter-packet interval, t_ipi, as follows:

\[ t_{\text{ipi}} = \frac{s}{X_{\text{inst}}} \]

Let \( t_{\text{now}} \) be the current time and \( i \) be a natural number, \( i = 0, 1, \ldots \), with \( t_i \) the nominal send time for the \( i \)-th packet. Then the nominal send time \( t_{i+1} \) would derive recursively as

\[
\begin{align*}
    t_0 &= t_{\text{now}}, \\
    t_{i+1} &= t_i + t_{\text{ipi}}.
\end{align*}
\]

For TFRC senders allowed to accumulate sending credits for unused sent time over the last \( T \) seconds, the sender would be allowed to use unused nominal sent times \( t_j \) for \( t_j < t_{\text{now}} - T \), for \( T \) set to the round-trip time.

5. Calculation of the Loss Event Rate (p)

Obtaining an accurate and stable measurement of the loss event rate is of primary importance for TFRC. Loss rate measurement is performed at the receiver, based on the detection of lost or marked packets from the sequence numbers of arriving packets. We describe this process before describing the rest of the receiver protocol. If the receiver has not yet detected a lost or marked packet, then the receiver doesn’t calculate the loss event rate, but reports a loss event rate of zero.

5.1. Detection of Lost or Marked Packets

TFRC assumes that all packets contain a sequence number that is incremented by one for each packet that is sent. For the purposes of this specification, we require that if a lost packet is retransmitted, the retransmission is given a new sequence number that is not the same as the sequence number as the packet that was lost. If a transport protocol has the requirement that it must retransmit with the original sequence number, then the transport protocol designer must figure out how to distinguish delayed from retransmitted packets and how to detect lost retransmissions.

The receiver maintains a data structure that keeps track of which packets have arrived and which are missing. For the purposes of
specification, we assume that the data structure consists of a list of packets that have arrived along with the receiver timestamp when each packet was received. In practice this data structure will normally be stored in a more compact representation, but this is implementation-specific.

The loss of a packet is detected by the arrival of at least NDUPACK packets with a higher sequence number than the lost packet, for NDUPACK set to 3. The requirement for NDUPACK subsequent packets is the same as with TCP, and is to make TFRC more robust in the presence of reordering. In contrast to TCP, if a packet arrives late (after NDUPACK subsequent packets arrived) in TFRC, the late packet can fill the hole in TFRC’s reception record, and the receiver can recalculate the loss event rate. Future versions of TFRC might make the requirement for NDUPACK subsequent packets adaptive based on experienced packet reordering, but we do not specify such a mechanism here.

For an ECN-capable connection, a marked packet is detected as a congestion event as soon as it arrives, without having to wait for the arrival of subsequent packets.

5.2. Translation from Loss History to Loss Events

TFRC requires that the loss fraction be robust to several consecutive packets lost or marked in the same loss event. This is similar to TCP, which (typically) only performs one halving of the congestion window during any single RTT. Thus the receiver needs to map the packet loss history into a loss event record, where a loss event is one or more packets lost or marked in an RTT. To perform this mapping, the receiver needs to know the RTT to use, and this is supplied periodically by the sender, typically as control information piggy-backed onto a data packet. TFRC is not sensitive to how the RTT measurement sent to the receiver is made, but we recommend using the sender’s calculated RTT, R, (see Section 4.3) for this purpose.

To determine whether a lost or marked packet should start a new loss event, or be counted as part of an existing loss event, we need to compare the sequence numbers and timestamps of the packets that arrived at the receiver. For a marked packet S_new, its reception time T_new can be noted directly. For a lost packet, we can interpolate to infer the nominal "arrival time". Assume:

\[ S\_loss \] is the sequence number of a lost packet.
S\_before is the sequence number of the last packet to arrive, before any packet arrivals with a sequence number above S\_loss, with a sequence number below S\_loss.

S\_after is the sequence number of the first packet to arrive after S\_before with a sequence number above S\_loss.

S\_max is the largest sequence number.

Therefore, S\_before < S\_loss < S\_after <= S\_max.

T\_loss is the nominal estimated arrival time for the lost packet.

T\_before is the reception time of S\_before.

T\_after is the reception time of S\_after.

Note that due to reordering, T\_before could be either before or after T\_after.

For a lost packet S\_loss, we can interpolate its nominal "arrival time" at the receiver from the arrival times of S\_before and S\_after. Thus:

\[
T\_loss = T\_before + ( (T\_after - T\_before) * (S\_loss - S\_before)/(S\_after - S\_before) );
\]

To address sequence number wrapping, let S\_MAX be the maximum sequence number using by the particular implementation. In this case, we can interpolate the arrival time T\_loss as follows:

\[
T\_loss = T\_before + (T\_after - T\_before) * \text{Dist}(S\_loss, S\_before)/\text{Dist}(S\_after, S\_before)
\]

where

\[
\text{Dist}(S\_A, S\_B) = (S\_A + S\_MAX - S\_B) \mod S\_MAX
\]

If the lost packet S\_old was determined to have started the previous loss event, and we have just determined that S\_new has been lost, then we interpolate the nominal arrival times of S\_old and S\_new, called T\_old and T\_new respectively.

If T\_old + R >= T\_new, then S\_new is part of the existing loss event. Otherwise S\_new is the first packet in a new loss event.
5.3. Inter-loss Event Interval

If a loss interval, A, is determined to have started with packet sequence number S_A and the next loss interval, B, started with packet sequence number S_B, then the number of packets in loss interval A is given by (S_B - S_A). Thus, loss interval A contains all of the packets transmitted by the sender starting with the first packet transmitted in loss interval A, and ending with but not including the first packet transmitted in loss interval B.

5.4. Average Loss Interval

To calculate the loss event rate p, we first calculate the average loss interval. This is done using a filter that weights the n most recent loss event intervals in such a way that the measured loss event rate changes smoothly. If the receiver has not yet seen a lost or marked packet, then the receiver doesn’t calculate the average loss interval.

Weights w_0 to w_(n-1) are calculated as:

\[
\text{If } (i < n/2) \{ \\
\quad w_i = 1; \\
\text{Else } \{ \\
\quad w_i = 2 \times (n-i)/(n+2); \\
\}
\]

Thus if n=8, the values of w_0 to w_7 are:

1.0, 1.0, 1.0, 1.0, 0.8, 0.6, 0.4, 0.2

The value n for the number of loss intervals used in calculating the loss event rate determines TFRC’s speed in responding to changes in the level of congestion. As currently specified, TFRC SHOULD NOT use values of n greater than 8, for traffic that might compete in the global Internet with TCP. At the very least, safe operation with values of n greater than 8 would require a slight change to TFRC’s mechanisms, to include a more severe response to two or more round-trip times with heavy packet loss.

When calculating the average loss interval we need to decide whether to include the current loss interval, defined as the loss interval containing the most recent loss event. We only include the current loss interval if it is sufficiently large to increase the average loss interval.
Let the most recent loss intervals be $I_0$ to $I_k$, where $I_0$ is the current loss interval. If there have been at least $n$ loss intervals, then $k$ is set to $n$; otherwise $k$ is the maximum number of loss intervals seen so far. We calculate the average loss interval $I_{\text{mean}}$ as follows:

$$
I_{\text{tot0}} = 0;
I_{\text{tot1}} = 0;
W_{\text{tot}} = 0;
$$

for $i = 0$ to $k-1$ {
    $$I_{\text{tot0}} = I_{\text{tot0}} + (I_i \times w_i);$$
    $$W_{\text{tot}} = W_{\text{tot}} + w_i;$$
}

for $i = 1$ to $k$ {
    $$I_{\text{tot1}} = I_{\text{tot1}} + (I_i \times w_{(i-1)});$$
}

$I_{\text{tot}} = \max(I_{\text{tot0}}, I_{\text{tot1}});$
$I_{\text{mean}} = I_{\text{tot}}/W_{\text{tot}};$

The loss event rate, $p$ is simply:

$$p = 1 / I_{\text{mean}};$$

5.5. History Discounting

As described in Section 5.4, when there have been at least eight loss intervals, the most recent loss interval is only assigned $1/(0.75 \times n)$ of the total weight in calculating the average loss interval, regardless of the size of the most recent loss interval. This section describes an optional history discounting mechanism, discussed further in [FHPW00a] and [W00], that allows the TFRC receiver to adjust the weights, concentrating more of the relative weight on the most recent loss interval, when the most recent loss interval is more than twice as large as the computed average loss interval.

To carry out history discounting, we associate a discount factor $DF_i$ with each loss interval $L_i$, for $i > 0$, where each discount factor is a floating point number. The discount array maintains the cumulative history of discounting for each loss interval. At the beginning, the values of $DF_i$ in the discount array are initialized to 1:

$$
\text{for } i = 0 \text{ to } n \{ \\
    DF_i = 1; \\
\}
$$
History discounting also uses a general discount factor $DF$, also a floating point number, that is also initialized to 1. First we show how the discount factors are used in calculating the average loss interval, and then we describe later in this section how the discount factors are modified over time.

As described in Section 5.4 the average loss interval is calculated using the $n$ previous loss intervals $I_1$, ..., $I_n$ and the current loss interval $I_0$. The computation of the average loss interval using the discount factors is a simple modification of the procedure in Section 5.4, as follows:

$$I_{\text{tot}0} = I_0 \ast w_0$$
$$I_{\text{tot}1} = 0;$$
$$W_{\text{tot}0} = w_0$$
$$W_{\text{tot}1} = 0;$$

for $i = 1$ to $n-1$ {
    $$I_{\text{tot}0} = I_{\text{tot}0} + (I_i \ast w_i \ast DF_i \ast DF);$$
    $$W_{\text{tot}0} = W_{\text{tot}0} + w_i \ast DF_i \ast DF;$$
}

for $i = 1$ to $n$ {
    $$I_{\text{tot}1} = I_{\text{tot}1} + (I_i \ast w_{(i-1)} \ast DF_i);$$
    $$W_{\text{tot}1} = W_{\text{tot}1} + w_{(i-1)} \ast DF_i;$$
}

$$p = \min(W_{\text{tot}0}/I_{\text{tot}0}, W_{\text{tot}1}/I_{\text{tot}1});$$

The general discounting factor $DF$ is updated on every packet arrival as follows. First, the receiver computes the weighted average $I_{\text{mean}}$ of the loss intervals $I_1$, ..., $I_n$:

$$I_{\text{tot}} = 0;$$
$$W_{\text{tot}} = 0;$$

for $i = 1$ to $n$ {
    $$W_{\text{tot}} = W_{\text{tot}} + w_{(i-1)} \ast DF_i;$$
    $$I_{\text{tot}} = I_{\text{tot}} + (I_i \ast w_{(i-1)} \ast DF_i);$$
}

$$I_{\text{mean}} = I_{\text{tot}} / W_{\text{tot}};$$

This weighted average $I_{\text{mean}}$ is compared to $I_0$, the size of current loss interval. If $I_0$ is greater than twice $I_{\text{mean}}$, then the new loss interval is considerably larger than the old ones, and the general discount factor $DF$ is updated to decrease the relative weight on the older intervals, as follows:
if (I_0 > 2 * I_mean) {
    DF = 2 * I_mean/I_0;
    if (DF < THRESHOLD) {
        DF = THRESHOLD;
    }
} else {
    DF = 1;
}

A nonzero value for THRESHOLD ensures that older loss intervals from
an earlier time of high congestion are not discounted entirely. We
recommend a THRESHOLD of 0.25. Note that with each new packet
arrival, I_0 will increase further, and the discount factor DF will
be updated.

When a new loss event occurs, the current interval shifts from I_0
to I_1, loss interval I_i shifts to interval I_(i+1), and the loss
interval I_n is forgotten. The previous discount factor DF has to
be incorporated into the discount array. Because DF_i carries the
discount factor associated with loss interval I_i, the DF_i array
has to be shifted as well. This is done as follows:

    for (i = 1 to n) {
        DF_i = DF * DF_i;
    }
    for (i = n-1 to 0 step -1) {
        DF_(i+1) = DF_i;
    }

I_0 = 1;
DF_0 = 1;
DF = 1;

This completes the description of the optional history discounting
mechanism. We emphasize that this is an optional mechanism whose
sole purpose is to allow TFRC to respond somewhat more quickly to
the sudden absence of congestion, as represented by a long current
loss interval.

6. Data Receiver Protocol

The receiver periodically sends feedback messages to the sender.
Feedback packets should normally be sent at least once per RTT,
unless the sender is sending at a rate of less than one packet per
RTT, in which case a feedback packet should be send for every data
packet received. A feedback packet should also be sent whenever a
new loss event is detected without waiting for the end of an RTT.
and whenever an out-of-order data packet is received that removes a loss event from the history.

If the sender is transmitting at a high rate (many packets per RTT) there may be some advantages to sending periodic feedback messages more than once per RTT as this allows faster response to changing RTT measurements, and more resilience to feedback packet loss.

If the receiver was sending \( k \) feedback packets per RTT, for \( k > 1 \), step (4) of Section 6.2 would be modified to set the feedback timer to expire after \( R_m/k \) seconds. However, each feedback packet would still report the receiver rate over the last RTT, not over a fraction of an RTT. In this document we do not specify the modifications that might be required for a receiver sending more than one feedback packet per RTT. We note that there is little gain from sending a large number of feedback messages per RTT.

6.1. Receiver Behavior When a Data Packet is Received

When a data packet is received, the receiver performs the following steps:

1) Add the packet to the packet history.

2) Check if done: If the new packet results in the detection of a new loss event, or if no feedback packet was sent when the feedback timer last expired, go to step 3). Otherwise, no action need be performed (unless the optimization in the next paragraph is used), so exit the procedure.

   An optimization might check to see if the arrival of the packet caused a hole in the packet history to be filled and consequently two loss intervals were merged into one. If this is the case, the receiver might also send feedback immediately. The effects of such an optimization are normally expected to be small.

3) Calculate \( p \): Let the previous value of \( p \) be \( p_{\text{prev}} \). Calculate the new value of \( p \) as described in Section 5.

4) Expire feedback timer?: If \( p > p_{\text{prev}} \), cause the feedback timer to expire, and perform the actions described in Section 6.2. If \( p \leq p_{\text{prev}} \) and no feedback packet was sent when the feedback timer last expired, cause the feedback timer to expire, and perform the actions described in Section 6.2. If \( p \leq p_{\text{prev}} \) and a feedback packet was sent when the feedback timer last...
6.2. Expiration of Feedback Timer

When the feedback timer at the receiver expires, the action to be taken depends on whether data packets have been received since the last feedback was sent.

For the m-th expiration of the feedback timer, let the maximum sequence number of a packet at the receiver so far be $S_m$, and the value of the RTT measurement included in packet $S_m$ be $R_m$. As described in Section 3.2.1, $R_m$ is the sender’s most recent estimate of the round trip time, as reported in data packets. If data packets have been received since the previous feedback was sent, the receiver performs the following steps:

1) Calculate the average loss event rate using the algorithm described in Section 5.

2) Calculate the measured receive rate, $X_{recv}$, based on the packets received within the previous $R_{(m-1)}$ seconds. This is performed whether the feedback timer expired at its normal time, or expired early due to a new lost or marked packet (i.e., step (3) in Section 6.1).

In the typical case, when the receiver is sending only one feedback packet per round-trip time and the feedback timer did not expire early due to a new lost packet, then the time interval since the feedback timer last expired would be $R_{(m-1)}$ seconds.

We note that when the feedback timer expires early due to a new lost or marked packet, the time interval since the feedback timer last expired is likely to be smaller than $R_{(m-1)}$ seconds.

For ease of implementation, if the time interval since the feedback timer last expired is not $R_{(m-1)}$ seconds, the receive rate MAY be calculated over a longer time interval, the time interval going back to the most recent feedback timer expiration that was at least $R_{(m-1)}$ seconds ago.

3) Prepare and send a feedback packet containing the information described in Section 3.2.2.

4) Restart the feedback timer to expire after $R_m$ seconds.
Note that rule 2) above gives a minimum value for the measured receive rate $X_{\text{recv}}$ of one packet per round-trip time. If the sender is limited to a sending rate of less than one packet per round-trip time, this will be due to the loss event rate, not from a limit imposed by the measured receive rate at the receiver.

If no data packets have been received since the last feedback was sent, then no feedback packet is sent, and the feedback timer is restarted to expire after $R_m$ seconds.

6.3. Receiver Initialization

The receiver is initialized by the first data packet that arrives at the receiver. Let the sequence number of this packet be $i$.

When the first packet is received:

- Set $p=0$.
- Set $X_{\text{recv}} = 0$.
- Prepare and send a feedback packet.
- Set the feedback timer to expire after $R_i$ seconds.

If the first data packet doesn’t contain an estimate $R_i$ of the round-trip time, then the receiver sends a feedback packet for every arriving data packet, until a data packet arrives containing an estimate of the round-trip time.

If the sender is using a coarse-grained timestamp that increments every quarter of a round-trip time, then a feedback timer is not needed, and the following procedure from RFC 4342 is used to determine when to send feedback messages.

- Whenever the receiver sends a feedback message, the receiver sets a local variable last_counter to the greatest received value of the window counter since the last feedback message was sent, if any data packets have been received since the last feedback message was sent.

- If the receiver receives a data packet with a window counter value greater than or equal to last_counter + 4, then the receiver sends a new feedback packet. ("Greater" and "greatest" are measured in circular window counter space.)
6.3.1. Initializing the Loss History after the First Loss Event

The number of packets until the first loss can not be used to compute the allowed sending rate directly, as the sending rate changes rapidly during this time. TFRC assumes that the correct data rate after the first loss is half of the maximum sending rate before the loss occurred. TFRC approximates this target rate $X_{\text{target}}$ by the maximum value in $X_{\text{recv_set}}$. (For slow-start, for a particular round-trip time, the sender’s sending rate is generally twice the receiver’s receive rate for data sent over the previous round-trip time.)

After the first loss, instead of initializing the first loss interval to the number of packets sent until the first loss, the TFRC receiver calculates the loss interval that would be required to produce the data rate $X_{\text{target}}$, and uses this synthetic loss interval to seed the loss history mechanism.

TFRC does this by finding some value $p$ for which the throughput equation in Section 3.1 gives a sending rate within 5% of $X_{\text{target}}$, given the round-trip time $R$, and the first loss interval is then set to $1/p$. If the receiver knows the segment size $s$ used by the sender, then the receiver can use the throughput equation for $X$; otherwise, the receiver can measure the receive rate in packets per second instead of bytes per second for this purpose, and use the throughput equation for $X_{\text{pps}}$. (The 5% tolerance is introduced simply because the throughput equation is difficult to invert, and we want to reduce the costs of calculating $p$ numerically.)

Special care is needed for initializing the first loss interval when the first data packet is lost or marked. When the first data packet is lost in TCP, the TCP sender retransmits the packet after the retransmit timer expires. If TCP’s first data packet is ECN-marked, the TCP sender resets the retransmit timer, and sends a new data packet only when the retransmit timer expires [RFC3168] (Section 6.1.2). For TFRC, if the first data packet is lost or ECN-marked, then the first loss interval consists of the null interval with no data packets. In this case, the loss interval length for this (null) loss interval should be set to give a similar sending rate to that of TCP.

When the first TFRC loss interval is null, meaning that the first data packet is lost or ECN-marked, in order to follow the behavior of TCP, TFRC wants the allowed sending rate to be 1 packet every two round-trip times, or equivalently, 0.5 packets per RTT. Thus, the TFRC receiver calculates the loss interval that would be required to produce the target rate $X_{\text{target}}$ of $0.5/R$ packets per second, for the round-trip time $R$, and uses this synthetic loss interval for the
The main advantage of a sender-based variant of TFRC is that the sender does not have to trust the receiver’s calculation of the packet loss rate. However, with the requirement of reliable delivery of loss information from the receiver to the sender, a sender-based TFRC would have much tighter constraints on the transport protocol in which it is embedded.

In contrast, the receiver-based variant of TFRC specified in this document is robust to the loss of feedback packets, and therefore does not require the reliable delivery of feedback packets. It is also better suited for applications where it is desirable to offload work from the server to the client as much as possible.

RFC 4340 and RFC 4342 together specify CCID 3, which can be used as a sender-based variant of TFRC. In CCID 3, each feedback packet from the receiver contains a Loss Intervals option, reporting the lengths of the most recent loss intervals. Feedback packets may also include the Ack Vector option, allowing the sender to determine exactly which packets were dropped or marked and to check the information reported in the Loss Intervals options. The Ack Vector option can also include ECN Nonce Echoes, allowing the sender to verify the receiver’s report of having received an unmarked data packet. The Ack Vector option allows the sender to see for itself which data packets were lost or ECN-marked, to determine loss intervals, and to calculate the loss event rate. Section 9 of RFC 4342 discusses issues in the sender verifying information reported by the receiver.

8. Implementation Issues

This document has specified the TFRC congestion control mechanism, for use by applications and transport protocols. This section mentions briefly some of the implementation issues.
8.1. Computing the Throughput Equation

For \( t_{RTO} = 4R \) and \( b = 1 \), the throughput equation in Section 3.1 can be expressed as follows:

\[
X_{\text{Bps}} = \frac{s}{R \cdot f(p)}
\]

for

\[
f(p) = \sqrt{2p/3} + (12\sqrt{3p/8} \cdot p \cdot (1+32p^2)).
\]

A table lookup could be used for the function \( f(p) \).

Many of the multiplications (e.g., \( q \) and \( 1-q \) for the round-trip time average, a factor of 4 for the timeout interval) are or could be by powers of two, and therefore could be implemented as simple shift operations.

8.2. Sender Behavior When a Feedback Packet is Received

This section discusses implementation issues for sender behavior when a feedback packet is received, from Section 4.3.

8.2.1. Determining If an Interval Was a Data-limited Interval

When a feedback packet is received, the sender has to determine if the entire interval covered by that feedback packet was a data-limited period. If the feedback packets all report the timestamp of the last data packet received, then let \( t_{\text{new}} \) be the timestamp reported by this feedback packet. Because all feedback packets cover an interval of at least a round-trip time, it is sufficient for the sender to determine if there was any time in the period \((t_{\text{old}}, t_{\text{new}}]\) when the sender was not data-limited, for \( R \) the sender’s estimate of the round-trip time, and for \( t_{\text{old}} \) set to \( t_{\text{new}} - R \). (This procedure estimates the interval covered by the feedback packet, rather than computing it exactly. This seems fine to us.)

The sender can estimate whether the sender was data-limited over the entire interval \((t_{\text{old}}, t_{\text{new}}]\) by keeping two variables NotLimited1 and NotLimited2, both representing times when the sender was *not* data-limited. To initialize, NotLimited1 and NotLimited2 are set to the first two segment transmission times (for transmission to the layer below) when the transport-layer sender was not data-limited. (That is, the transport-layer sender had enough data to send all of the segments that it was allowed to send.) When possible, the
sender maintains NotLimited1 as a transmission time later than \( t_{\text{old}} \) when the sender was not data-limited, and maintains NotLimited2 as the earliest transmission time later than \( t_{\text{new}} \) when the sender was not data-limited.

When a feedback packet is received, first \( t_{\text{old}} \) and \( t_{\text{new}} \) are updated. If neither NotLimited1 nor NotLimited2 is in the interval \([t_{\text{old}}, t_{\text{new}}]\), then the sender assumes that it was data-limited over the entire interval covered by the feedback packet. NotLimited1 can then be updated as follows:

\[
\text{If } (\text{NotLimited1} \leq t_{\text{old}} \&\& \text{NotLimited2} > t_{\text{old}}) \{
\text{NotLimited1} = \text{NotLimited2};
\}
\]

We note that this procedure is a heuristic, and in some cases the sender might not determine correctly if the sender was data-limited over the entire interval covered by the feedback packet. In particular, this procedure does not address the possible complications of reordering. That seems fine to us.

In some implementations of TFRC, the sender sends coarse-grained timestamps that increment every quarter of a round-trip time, and the feedback packet reports the greatest valid sequence number received so far instead of reporting the timestamp of the last packet received. In this case, the sender can maintain per-packet state to determine \( t_{\text{new}} \) (the time that the acknowledged packet was sent), or the sender can estimate \( t_{\text{new}} \) from its estimate of the round-trip time and the elapsed time \( t_{\text{delay}} \) reported by the feedback packet.

8.2.2. Maintaining \( X_{\text{recv}} \_\text{set} \)

To reduce the complexity of maintaining \( X_{\text{recv}} \_\text{set} \), it is sufficient to limit \( X_{\text{recv}} \_\text{set} \) to at most \( N=3 \) elements. In this case, the subroutine Update \( X_{\text{recv}} \_\text{set} \) would be modified as follows:

\[
\text{Update } X_{\text{recv}} \_\text{set}:
\text{Add } X_{\text{recv}} \text{ to } X_{\text{recv}} \_\text{set};
\text{Delete from } X_{\text{recv}} \_\text{set} \text{ values older than two round-trip times.}
\text{Keep only the most recent } N \text{ values.}
\]

Maintaining at most *two* elements in \( X_{\text{recv}} \_\text{set} \) would be sufficient for the sender to save an old value of \( X_{\text{recv}} \) from before a data-limited period, and to allow the sender not to be limited by the first feedback packet after an idle period (reporting a receive rate of one packet per round-trip time). However, it is *possible* that...
maintaining at most two elements in X_recv_set would not give quite as good performance as maintaining at most three elements. Maintaining three elements in X_recv_set would allow X_recv_set to contain X_recv values from two successive feedback packets, plus a more recent X_recv value from a loss event.

8.3. Sending Packets Before their Nominal Send Time

This section discusses possible scheduling mechanisms for a sender in an operating system with a coarse-grained timing granularity (from Section 4.6).

Let t_gran be the scheduling timer granularity of the operating system. Let t_ipi be the inter-packet interval, as specified in Section 4.6. If the operating system has a coarse timer granularity or otherwise cannot support short t_ipi intervals, then either the TFRC sender will be restricted to a sending rate of at most 1 packet every t_gran seconds, or the TFRC sender must be allowed to send short bursts of packets. In addition to allowing the sender to accumulate sending credits for past unused send times, it can be useful to allow the sender to send a packet before its scheduled send time, as described in the section below.

A parameter t_delta MAY be used to allow a packet to be sent before its nominal send time. Consider an application that becomes idle and requests re-scheduling for time t_i = t_(i-1) + t_ipi, for t_(i-1) the send time for the previous packet. When the application is re-scheduled, it checks the current time, t_now. If (t_now > t_i - t_delta) then packet i is sent. When the nominal send time, t_i, of the next packet is calculated, it may already be the case that t_now > t_i - t_delta. In such a case the packet would be sent immediately.

In order to send at most one packet before its nominal send time, and never to send a packet more than a round-trip time before its nominal send time the parameter t_delta would be set as follows:

\[
    t_{\text{delta}} = \min(t_{\text{ipi}}, t_{\text{gran}}, \text{rtt})/2;
\]

(The scheduling granularity t_gran is 10 ms on some older Unix systems.)

As an example, consider a TFRC flow with an allowed sending rate X of 10 packets per round-trip time, a round-trip time of 100 ms, a system with a scheduling granularity t_gran of 10 ms, and the ability to accumulate unused sending credits for a round-trip time. In this case, t_ipi is 1 ms. The TFRC sender would be allowed to send packets 0.5 ms before their nominal sending time, and would be
allowed to save unused sending credits for 100 ms. The scheduling
granularity of 10 ms would not significantly affect the performance
of the connection.

As a different example, consider a TFRC flow with a scheduling
granularity greater than the round-trip time, for example, with a
round-trip time of 0.1 ms and a system with a scheduling granularity
of 1 ms, and with the ability to accumulate unused sending credits
for a round-trip time. The TFRC sender would be allowed to save
unused sending credits for 0.1 ms. If the scheduling granularity
*did not* affect the sender’s response to an incoming feedback
packet, then the TFRC sender would be able to send an RTT of data
(as determined by the allowed sending rate) each RTT, in response to
incoming feedback packets. In this case, the coarse scheduling
granularity would not significantly reduce the sending rate, but the
sending rate would be bursty, with a round-trip time of data sent in
response to each feedback packet.

However, performance would be different in this case if the
operating system scheduling granularity affected the sender’s
response to feedback packets as well as the general scheduling of
the sender, In this case the sender’s performance would be severely
limited by the scheduling granularity being greater than the round-
trip time, with the sender able to send an RTT of data, at the
allowed sending rate, at most once every 1 ms. This restriction of
the sending rate is an unavoidable consequence of allowing
burstiness of at most a round-trip time of data.

8.4. Calculation of the Average Loss Interval

The calculation of the average loss interval in Section 5.4 involves
multiplications by the weights w_0 to w_(n-1), which for n=8 are:

1.0, 1.0, 1.0, 1.0, 0.8, 0.6, 0.4, 0.2.

With a minor loss of smoothness, it would be possible to use weights
that were powers of two or sums of powers of two, e.g.,

1.0, 1.0, 1.0, 1.0, 0.75, 0.5, 0.25, 0.25.

8.5. The Optional History Discounting Mechanism

The optional history discounting mechanism described in Section 5.5
is used in the calculation of the average loss rate. The history
discounting mechanism is invoked only when there has been an
unusually long interval with no packet losses. For a more efficient
operation, the discount factor DF_i could be restricted to be a
power of two.
9. Changes from RFC 3448

9.1. Overview of Changes

This section summarizes the changes from RFC 3448. At a high level, the main change is to add mechanisms to address the case of a data-limited sender. This document also explicitly allows the TFRC sender to accumulate up to a round-trip time of unused send credits, and as a result to send a burst of packets if data arrives from the application in a burst after a data-limited period. This issue was not explicitly addressed in RFC 3448.

This document updates RFC 3448 to incorporate TCP’s higher initial sending rates from RFC 3390. This document also updates RFC 3448 to incorporate RFC 4243’s use of a coarse-grained timestamp on data packets instead of a more fine-grained timestamp.

Other changes address corner cases involving slow-start, the response when the first data packet is dropped, and the like. This document also incorporates the items in the RFC 3448 Errata.

This section is non-normative; the normative text is in the cited sections.

9.2. Changes in each Section

Section 4.1, estimating the average segment size: Section 4.1 was modified to give a specific algorithm that could be used for estimating the average segment size.

Section 4.2, update to the initial sending rate: In RFC 3448, the initial sending rate was two packets per round trip time. In this document, the initial sending rate can be as high as four packets per round trip time, following RFC 3390. The initial sending rate was changed to be in terms of the segment size s, not in terms of the MSS.

Section 4.2 now says that tld, the Time Last Doubled during slow-start, can be initialized to either 0 or to -1. Section 4.2 was also clarified to say that RTT measurements do not only come from feedback packets; they could also come from other places, such as the SYN exchange.

Section 4.3, response to feedback packets: Section 4.3 was modified to change the way that the receive rate is used in limiting the sender’s allowed sending rate, by using the set of receive rate values of the last two round-trip times, and initializing the set of
receive rate values by a large value.

The larger initial sending rate in Section 4.2 is of little use if the receiver sends a feedback packet after the first packet is received, and the sender in response reduces the allowed sending rate to at most two packets per RTT, which would be twice the receive rate. Because of the change in the sender’s processing of the receive rate, the sender now does not reduce the allowed sending rate to twice the reported receive rate in response to the first feedback packet.

The sender doesn’t double the allowed sending rate during slow-start if the sender has been data-limited over the entire interval reported by the feedback packet.

During a data-limited period, the sender saves the receive rate reported from just before the data-limited period, if it is larger than the receive rate during the data-limited period. Thus, the sender does not use the receive rate from a data-limited period to restrict the allowed sending rate. Appendix C discusses this response further.

Section 4.4, response to an idle period: Following Section 5.1 from [RFC4342], this document specifies that when the sending rate is reduced after an idle period that covers the period since the nofeedback timer was set, the allowed sending rate is not reduced below the initial sending rate. (In Section 4.4, the variable recover_rate is set to the initial sending rate.)

Section 4.4, correction from [RFC3448Err]. RFC 3448 had contradictory text about whether the sender halved its sending rate after *two* round-trip times without receiving a feedback report, or after *four* round-trip times. This document clarifies that the sender halves its sending rate after four round-trip times without receiving a feedback report [RFC3448Err].

Section 4.4, clarification for Slow-Start: Section 4.4 was clarified to specify that on the expiration of the nofeedback timer, if p = 0, X_Bps can’t be used, because the sender doesn’t yet have a value for X_Bps. Section 4.4 was also clarified to check the case when the sender doesn’t yet have an RTT sample, but has sent a packet since the nofeedback timer was set.

Section 4.6: credits for unused send time:

Section 4.6 has been clarified to say that the TFRC sender gets to accumulate up to an RTT of credits for unused send time. Section 4.6 was also rewritten to clarify what is specification and what is
implementation.

Section 5.4, clarification: Section 5.4 was modified to clarify the receiver’s calculation of the average loss interval when the receiver has not yet seen eight loss intervals.

Section 5.5, correction: Section 5.5 was corrected to say that the loss interval \( I_0 \) includes all transmitted packets, including lost and marked packets (as defined in Section 5.3 in the general definition of loss intervals.)

Section 5.5, correction from [RFC3448Err]: A line in Section 5.5 was changed from

to

[RFC3448Err].

Section 5.5, history discounting: THRESHOLD, the lower bound on the history discounting parameter \( DF \), has been changed from 0.5 to 0.25, to allow more history discounting when the current interval is long.

Section 6, multiple feedback packets: Section 6 now contains more discussion of procedures if the receiver sends multiple feedback packets each round-trip time.

Section 6.3, initialization of the feedback timer: Section 6.3 now specifies the receiver’s initialization of the feedback timer if the first data packet received doesn’t have an estimate of the round-trip time.

Section 6.3, a coarse-grained timestamp: Section 6.3 was modified to incorporate, as an option, a coarse-grained timestamp from the sender that increments every quarter of a round-trip time, instead of a more fine-grained timestamp. This follows RFC 4243.

Section 6.3.1, after the first loss event: Section 6.3.1 now says that for initializing the loss history after the first loss event, the receiver uses the maximum receive rate in \( X_{recv\_set} \), instead of the receive rate in the last round-trip time.

Section 6.3.1, if the first data packet is dropped: Section 6.3.1 now contains a specification for initializing the loss history if the first data packet sent is lost or ECN-marked.

Section 7, sender-based variants: Section 7’s discussion of sender-
based variants has been expanded, with reference to RFC 4342.

10. Security Considerations

TFRC is not a transport protocol in its own right, but a congestion control mechanism that is intended to be used in conjunction with a transport protocol. Therefore security primarily needs to be considered in the context of a specific transport protocol and its authentication mechanisms.

Congestion control mechanisms can potentially be exploited to create denial of service. This may occur through spoofed feedback. Thus any transport protocol that uses TFRC should take care to ensure that feedback is only accepted from the receiver of the data. The precise mechanism to achieve this will however depend on the transport protocol itself.

In addition, congestion control mechanisms may potentially be manipulated by a greedy receiver that wishes to receive more than its fair share of network bandwidth. A receiver might do this by claiming to have received packets that in fact were lost due to congestion. Possible defenses against such a receiver would normally include some form of nonce that the receiver must feed back to the sender to prove receipt. However, the details of such a nonce would depend on the transport protocol, and in particular on whether the transport protocol is reliable or unreliable.

We expect that protocols incorporating ECN with TFRC will also want to incorporate feedback from the receiver to the sender using the ECN nonce [RFC3540]. The ECN nonce is a modification to ECN that protects the sender from the accidental or malicious concealment of marked packets. Again, the details of such a nonce would depend on the transport protocol, and are not addressed in this document.

11. IANA Considerations

There are no IANA actions required for this document.

12. Acknowledgments

We would like to acknowledge feedback and discussions on equation-based congestion control with a wide range of people, including members of the Reliable Multicast Research Group, the Reliable Multicast Transport Working Group, and the End-to-End Research Group. We would like to thank Dado Colussi, Gorry Fairhurst, Ladan
A. Terminology

This document uses the following terms. Timer variables (e.g., \( t_{\text{now}} \), \( t_{\text{ld}} \)) are assumed to be in seconds, with a timer resolution of at least a millisecond.

\textbf{data-limited interval:}

An interval where the sender is data-limited (not sending as much as it is allowed to send) over the entire interval (Section 4.3).

\textbf{DF:} Discount factor for a loss interval (Section 5.5).

\textbf{initial_rate:}

Allowed initial sending rate.

\textbf{last_counter:}

Greatest received value of the window counter (Section 6.3).

\textbf{min_rate:}

Minimum transmit rate (Section 4.3).

\textbf{n:} Number of loss intervals.

\textbf{NDUPACK:}

Number of dupacks for inferring loss (constant) (Section 5.1).

\textbf{nofeedback timer:}

Sender-side timer (Section 4).

\textbf{p:} Estimated Loss Event Rate.

\textbf{p_{\text{prev}}:}

Previous value of \( p \) (Section 6.1).

\textbf{q:} Filter constant for RTT (constant) (Section 4.3).

\textbf{q_{2:}} Filter constant for long-term RTT (constant) (Section 4.6).
R: Estimated path round-trip time.

R_m:
A specific estimate of the path round-trip time (Sections 4.3, 6).

R_sample:
Measured path RTT (Section 4.3).

R_sqmean:
Long-term estimate of the square root of the RTT (Section 4.6).

recover_rate:
Allowed rate for resuming after an idle period (Section 4.4).

recv_limit;
Limit on sending rate computed from the receive rate (Section 4.3).

s: Nominal packet size in bytes.

S: Sequence number.

t_delay:
Reported time delay between receipt of the last packet at the receiver and the generation of the feedback packet (Section 3.2.2).

t_delta:
Parameter for flexibility in send time (Section 8.3).

t_gran:
Scheduling timer granularity of the operating system (constant) (Section 8.3).

t_ipi:
Inter-packet interval for sending packets (Section 4.6).

t_mbi:
Maximum RTO value of TCP (constant) (Section 4.3).

t_recvdata:
Timestamp of the last data packet received (Section 3.2.2).

timer_limit:
Limit on the sending rate from the expiration of the nofeedback timer (Section 4.4).
tld:
    Time Last Doubled (Section 4.2).

t_now:
    Current time (Section 4.3).

t_RTO:
    Estimated RTO of TCP (Section 4.3).

X:  Allowed transmit rate, as limited by the receive rate.

X_Bps:
    Calculated sending rate in bytes per second (Section 3.1).

X_pps:
    Calculated sending rate in packets per second (Section 3.1).

X_inst:
    Instantaneous allowed transmit rate (Section 4.6).

X_recv:
    Estimated receive rate at the receiver (Section 3.2.2).

X_recv_set:
    A small set of recent X_recv values (Section 4.3).

X_target:
    The target sending rate after the first loss event (Section 6.3.1).

W_init:
    TCP initial window (constant) (Section 4.2).

B. The Initial Value of the Nofeedback Timer

Why is the initial value of TFRC’s nofeedback timer set to two seconds, instead of the recommended initial value of three seconds for TCP’s retransmit timer, from [RFC2988]? There is not any particular reason why TFRC’s nofeedback timer should have the same initial value as TCP’s retransmit timer. TCP’s retransmit timer is used not only to reduce the sending rate in response to congestion, but also to retransmit a packet that is assumed to have been dropped in the network. In contrast, TFRC’s nofeedback timer is only used to reduce the allowed sending rate, not to trigger the sending of a new packet. As a result, there is no danger to the network for the initial value of TFRC’s nofeedback timer to be smaller than the recommended initial value for TCP’s retransmit timer.
Further, when the nofeedback timer has not yet expired, TFRC has a less slowly-responding congestion control mechanism than TCP, and TFRC’s use of the receive rate for limiting the sending rate is somewhat less precise than TCP’s use of windows and ack-clocking, so the nofeedback timer is a particularly important safety mechanism for TFRC. For all of these reasons, it is perfectly reasonable for TFRC’s nofeedback timer to have a smaller initial value than that of TCP’s retransmit timer.

C. Response to Idle or Data-limited Periods

Future work could explore alternate responses to using the receive rate during a data-limited period.

In particular, Congestion Window Validation (CWV) for TCP is specified in [RFC2861], an Experimental RFC. For this discussion, we use the term "Standard TCP" to refer to the TCP congestion control mechanisms in [RFC2581] and [RFC2581bis]. [RFC2861] specifies a different response to idle or data-limited periods than those of Standard TCP. With CWV, the TCP sender halves the congestion window after each RTO during an idle period, down to the initial window. Similarly, with CWV the TCP sender halves the congestion window half-way down to the flight size after each RTO during a data-limited period.

This document already specifies a TFRC response to idle periods that is similar to that of TCP with Congestion Window Validation. However, this document does not specify a TFRC response to data-limited periods similar to that of CWV. Adding such a mechanism to TFRC would require a one-line change to step (4) of Section 4.3. In particular, the sender’s response to a feedback packet would be changed from:

```
If (the entire interval covered by the feedback packet
 was a data-limited interval) {
  Maximize X_recv_set;
}
```

to:

```
If (the entire interval covered by the feedback packet
 was a data-limited interval) {
  Multiply old entries in X_recv_set by 0.85;
  Maximize X_recv_set;
}
```
In particular, if the receive rate from before a data-limited period is saved in X_recv_set, then the change in step (4) above would multiply that receive rate by 0.85 each time that a feedback packet is received and the above code is executed. As a result, after four successive round-trip times of data-limited intervals, the receive rate from before the data-limited period would be reduced by 0.85^4 = 0.52. Thus, this one-line change to step (4) of Section 4.3 would result in the allowed sending rate being halved for each four roundtrip times in which the sender was data-limited. Because of the nature of X_recv_set, this mechanism would never reduce the allowed sending rate below twice the most recent receive rate.

C.1. Long Idle or Data-limited Periods

Table 1 summarizes the response of Standard TCP [RFC2581], TCP with Congestion Window Validation [RFC2861], Standard TFRC [RFC3448], and Revised TFRC (this document) in response to long idle or data-limited periods. For the purposes of this section, we define a long period as a period of at least an RTO.

<table>
<thead>
<tr>
<th>Protocol</th>
<th>Long idle periods</th>
<th>Long data-limited periods</th>
</tr>
</thead>
<tbody>
<tr>
<td>Standard TCP:</td>
<td>Window -&gt; initial.</td>
<td>No change in window.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>(Window not increased in data-limited periods.)</td>
</tr>
<tr>
<td>TCP with CWV:</td>
<td>Halve window</td>
<td>Reduce window half way</td>
</tr>
<tr>
<td></td>
<td>(not below initial cwnd).</td>
<td>to used window.</td>
</tr>
<tr>
<td>Standard TFRC:</td>
<td>Halve rate</td>
<td>Rate limited to twice</td>
</tr>
<tr>
<td></td>
<td>(not below 2 pkts/rtt).</td>
<td>receive rate.</td>
</tr>
<tr>
<td></td>
<td>One RTT after sending pkt, rate is limited by X_recv.</td>
<td></td>
</tr>
<tr>
<td>Revised TFRC:</td>
<td>Halve rate</td>
<td>Rate limited to twice</td>
</tr>
<tr>
<td></td>
<td>(not below initial rate).</td>
<td>max(current receive rate, receive rate before data-limited period).</td>
</tr>
</tbody>
</table>

Table 1: Response to long idle or data-limited periods.

Standard TCP after long idle periods: For Standard TCP, [RFC2581] specifies that TCP SHOULD set the congestion window to no more than the initial window after an idle period of at least an RTO. (To be precise, RFC 2581 specifies that the TCP sender should set cwnd to the initial window if the sender has not sent data in an interval exceeding the retransmission timeout.)
Standard TCP after long data-limited periods: Standard TCP [RFC2581] does not reduce TCP’s congestion window after a data-limited period, when the congestion window is not fully used. Standard TCP in [RFC2581] uses the FlightSize, the amount of outstanding data in the network, only in setting the slow-start threshold after a retransmit timeout. Standard TCP is not limited by TCP’s ack-clocking mechanism during a data-limited period.

Standard TCP’s lax response to a data-limited period is quite different from its stringent response to an idle period.

TCP with Congestion Window Validation (CWV) after long idle periods: As an experimental alternative, [RFC2861] specifies a more moderate response to an idle period than that of Standard TCP, where during an idle period the TCP sender halves cwnd after each RTO, down to the initial cwnd.

TCP with Congestion Window Validation after long data-limited periods: As an experimental alternative, [RFC2861] specifies a more stringent response to a data-limited period than that of Standard TCP, where after each RTO seconds of a data-limited period, the congestion window is reduced half way down to the window that is actually used.

The response of TCP with CWV to an idle period is similar to its response to a data-limited period. TCP with CWV is less restrictive than Standard TCP in response to an idle period, and more restrictive than Standard TCP in response to a data-limited period.

Standard TFRC after long idle periods: For Standard TFRC, [RFC3448] specifies that the allowed sending rate is halved after each RTO seconds of an idle period. The allowed sending rate is not reduced below two packets per RTT after idle periods. After an idle period, the first feedback packet received reports a receive rate of one packet per round-trip time, and this receive rate is used to limit the sending rate. Standard TFRC effectively slow-starts up from this allowed sending rate.

Standard TFRC after long data-limited periods: [RFC3448] does not distinguish between data-limited and non-data-limited periods. As a consequence, the allowed sending rate is limited to at most twice the receive rate during and after a data-limited period. This is a very restrictive response, more restrictive than that of either Standard TCP or of TCP with CWV.

Revised TFRC after long idle periods: For Revised TFRC, this document specifies that the allowed sending rate is halved after each RTO seconds of an idle period. The allowed sending rate is not
reduced below the initial sending rate as the result of an idle period. The first feedback packet received after the idle period reports a receive rate of one packet per round-trip time. However, the Revised TFRC sender does not use this receive rate for limiting the sending rate. Thus, Revised TFRC differs from Standard TFRC in the lower limit used in the reduction of the sending rate, and in the better response to the first feedback packet received after the idle period.

Revised TFRC after long data-limited periods: For Revised TFRC, this document distinguishes between data-limited and non-data-limited periods. As specified in Section 4.3, during a data-limited period Revised TFRC remembers the receive rate before the data-limited period began, and does not reduce the allowed sending rate below twice that receive rate. This is somewhat similar to the response of Standard TCP, and is quite different from the very restrictive response of Standard TFRC to a data-limited period. However, the response of Revised TFRC is not as conservative as the response of TCP with Congestion Window Validation, where the congestion window is gradually reduced down to the window actually used during a data-limited period.

We note that for Standard TCP, the congestion window is generally not increased during a data-limited period (when the current congestion window is not being fully used). We note that there is no mechanism comparable to this in Revised TFRC.

Recovery after idle or data-limited periods: When TCP reduces the congestion window after an idle or data-utilized period, TCP can set the slow-start threshold ssthresh to allow the TCP sender to slow-start back up towards its old sending rate when the idle or data-limited period is over. However in TFRC, even when the TFRC sender’s sending rate is restricted by twice the previous receive rate, this results in the sender being able to double the sending rate from one round-trip time to the next, if permitted by the throughput equation. Thus, TFRC doesn’t need a mechanism such as TCP’s setting of ssthresh to allow a slow-start after an idle or data-limited period.

For future work, one avenue to explore would be the addition of Congestion Window Validation mechanisms for TFRC’s response to data-limited periods. Currently, following Standard TCP, during data-limited periods Revised TFRC does not limit its allowed sending rate as a function of the receive rate.
C.2. Short Idle or Data-limited Periods

Table 2 summarizes the response of Standard TCP [RFC2581], TCP with Congestion Window Validation [RFC2861], Standard TFRC [RFC3448], and Revised TFRC (this document) in response to short idle or data-limited periods. For the purposes of this section, we define a short period as a period of less than an RTT.

<table>
<thead>
<tr>
<th>Protocol</th>
<th>Short idle periods</th>
<th>Short data-limited periods</th>
</tr>
</thead>
<tbody>
<tr>
<td>Standard TCP:</td>
<td>Send a burst up to cwnd.</td>
<td>Send a burst up to cwnd.</td>
</tr>
<tr>
<td>TCP with CWV:</td>
<td>Send a burst up to cwnd.</td>
<td>Send a burst up to cwnd.</td>
</tr>
<tr>
<td>Standard TFRC:</td>
<td>?</td>
<td>?</td>
</tr>
<tr>
<td>Revised TFRC:</td>
<td>Send a burst (up to an RTT of unused send credits).</td>
<td>Send a burst (up to an RTT of unused send credits).</td>
</tr>
</tbody>
</table>

Table 2: Response to short idle or data-limited periods.

Table 2 shows that Revised TFRC has a similar response to that of Standard TCP and of TCP with CWV to a short idle or data-limited period. For a short idle or data-limited period, TCP is limited only by the size of the unused congestion window, and Revised TFRC is limited only by the number of unused send credits (up to an RTT’s worth). For Standard TFRC, [RFC3448] did not explicitly specify the behavior with respect to unused send credits.

C.3. Moderate Idle or Data-limited Periods

Table 3 summarizes the response of Standard TCP [RFC2581], TCP with Congestion Window Validation [RFC2861], Standard TFRC [RFC3448], and Revised TFRC (this document) in response to moderate idle or data-limited periods. For the purposes of this section, we define a moderate period as a period greater than an RTT, but less than an RTO.
Table 3: Response to moderate idle or data-limited periods.

<table>
<thead>
<tr>
<th>Protocol</th>
<th>Moderate idle periods</th>
<th>Moderate data-limited periods</th>
</tr>
</thead>
<tbody>
<tr>
<td>Standard TCP:</td>
<td>Send a burst up to cwnd.</td>
<td>Send a burst up to cwnd.</td>
</tr>
<tr>
<td>TCP with CWV:</td>
<td>Send a burst up to cwnd.</td>
<td>Send a burst up to cwnd.</td>
</tr>
<tr>
<td>Standard TFRC:</td>
<td>?</td>
<td>Limited by (X_{recv}).</td>
</tr>
<tr>
<td>Revised TFRC:</td>
<td>Send a burst (\text{(up to an RTT of unused send credits)}).</td>
<td>Send a burst (\text{(up to an RTT of unused send credits)}).</td>
</tr>
</tbody>
</table>

Table 3 shows that Revised TFRC has a similar response to that of Standard TCP and of TCP with CWV to a moderate idle or data-limited period. For a moderate idle or data-limited period, TCP is limited only by the size of the unused congestion window. For a moderate idle period, Revised TFRC is limited only by the number of unused send credits (up to an RTT’s worth). For a moderate data-limited period, Standard TFRC would be limited by \(X_{recv}\) from the most recent feedback packet. In contrast, Revised TFRC is not limited by the receive rate from data-limited periods that cover an entire feedback period of a round-trip time. For Standard TFRC, [RFC3448] did not explicitly specify the behavior with respect to unused send credits.

C.4. Other Patterns

Other possible patterns to consider in evaluating Revised TFRC would be to compare the behavior of TCP, Standard TFRC, and Revised TFRC for connections with alternating busy and idle periods, alternating idle and data-limited periods, or with idle or data-limited periods during Slow-Start.

C.5. Evaluating TFRC’s Response to Idle Periods

In this section we focus on evaluating Revised TFRC’s response to idle or data-limited periods.

One drawback to Standard TFRC’s strict response to idle or data-limited periods is that it could be seen as encouraging applications to pad their sending rate during idle or data-limited periods, by sending dummy data when there was no other data to send. Because Revised TFRC has a less strict response to data-limited periods than that of Standard TFRC, TFRC also could be seen as giving applications less of an incentive to pad their sending rates during data-limited periods. Work in progress such as Faster Restart
[KFS07] can also decrease an application’s incentive to pad its sending rate, by allowing faster start-up after idle periods. Further research would be useful to understand in more detail the interaction between TCP or TFRC’s congestion control mechanisms, and an application’s incentive to pad its sending rate during idle or data-limited periods.

TCP Congestion Window Validation, described in Appendix C.1 above, is an Experimental standard specifying that the TCP sender slowly reduces the congestion window during an idle or data-limited period [RFC2861]. While TFRC and Revised TFRC’s responses to idle periods are roughly similar to those of TCP with Congestion Window Validation, Revised TFRC’s response to data-limited periods is less conservative than those of TCP with Congestion Window Validation (and Standard TFRC’s response to data-limited periods was considerably *more* conservative than those of Congestion Window Validation). Future work could include modifications to this document so that the response of Revised TFRC to a data-limited period includes a slow reduction of the allowed sending rate; Section C specifies a possible mechanism for this. Such a modification would be particularly compelling if Congestion Window Validation became a Proposed Standard in the IETF for TCP.

Normative References


Informational References


[KFS07] E. Kohler, S. Floyd, and A. Sathiaseelan, Faster Restart for TCP Friendly Rate Control (TFRC), Internet-draft draft-ietf-dccp-tfrc-faster-


[RFC2119] S. Bradner, Key Words For Use in RFCs to Indicate Requirement Levels, RFC 2119.


Authors’ Addresses

Mark Handley,
Department of Computer Science
University College London
Gower Street
London WC1E 6BT
UK
EMail: M.Handley@cs.ucl.ac.uk

Sally Floyd
ICSI
1947 Center St, Suite 600
Berkeley, CA 94708
Email: floyd@icir.org

Jitendra Padhye
Microsoft Research
Email: padhye@microsoft.com

Joerg Widmer
DoCoMo Euro-Labs
Landsberger Strasse 312
80687 Munich
Germany
Email: widmer@acm.org

Full Copyright Statement

Copyright (C) The IETF Trust (2008).

This document is subject to the rights, licenses and restrictions contained in BCP 78, and except as set forth therein, the authors
This document and the information contained herein are provided on an "AS IS" basis and THE CONTRIBUTOR, THE ORGANIZATION HE/SHE REPRESENTS OR IS SPONSORED BY (IF ANY), THE INTERNET SOCIETY, THE IETF TRUST AND THE INTERNET ENGINEERING TASK FORCE DISCLAIM ALL WARRANTIES, EXPRESS OR IMPLIED, INCLUDING BUT NOT LIMITED TO ANY WARRANTY THAT THE USE OF THE INFORMATION HEREIN WILL NOT INFRINGE ANY RIGHTS OR ANY IMPLIED WARRANTIES OF MERCHANTABILITY OR FITNESS FOR A PARTICULAR PURPOSE.

Intellectual Property

The IETF takes no position regarding the validity or scope of any Intellectual Property Rights or other rights that might be claimed to pertain to the implementation or use of the technology described in this document or the extent to which any license under such rights might or might not be available; nor does it represent that it has made any independent effort to identify any such rights. Information on the procedures with respect to rights in RFC documents can be found in BCP 78 and BCP 79.

Copies of IPR disclosures made to the IETF Secretariat and any assurances of licenses to be made available, or the result of an attempt made to obtain a general license or permission for the use of such proprietary rights by implementers or users of this specification can be obtained from the IETF on-line IPR repository at http://www.ietf.org/ipr.

The IETF invites any interested party to bring to its attention any copyrights, patents or patent applications, or other proprietary rights that may cover technology that may be required to implement this standard. Please address the information to the IETF at ietf-ipr@ietf.org.